

Field-Sensitive Unreachability and Non-Cyclicity Analysis

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Static Analysis

Definition

Static analysis consists in building compile-time techniques in order to prove properties of programs **before actually running them**.

Shape Analyses try to understand how the program execution manipulates the heap.

e.g.,

- *sharing analysis* determines if two variables might be bound to overlapping data structures.
- *reachability analysis* determines if exists a path in memory that links two variables.
- *cyclicity analysis* determines if a variable is bound to a cyclical data structure.

State of the Art

Reachability and Cyclicity, state of the art:

- Stefano Rossignoli and Fausto Spoto, "*Detecting non-cyclicity by abstract compilation into boolean functions*". In: VMCAI'06
- Samir Genaim and Damiano Zanardini, "*Reachability-based Acyclicity Analysis by Abstract Interpretation*". In: CoRR'12
- Đurica Nikolić and Fausto Spoto, "*Reachability Analysis of Program Variables*". In: IJCAR'12

`x.next=y;`

This assignment makes `x` *cyclical* if and only if `y` reaches `x`.

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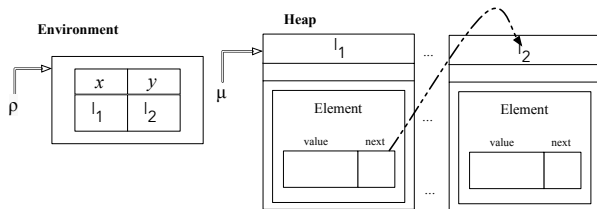
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We defined a state as $\sigma = \langle \rho, \mu \rangle$, where:

- ρ maps variables to locations;
- μ binds locations to objects.



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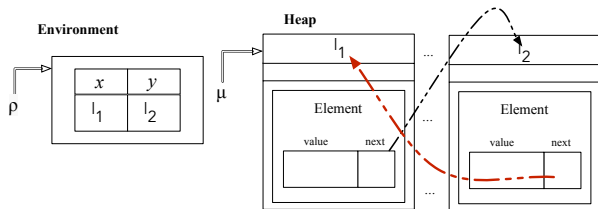
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Scenario

Given the following Java instructions,

```
while (x != null)
    x = x.next;
```

Does the loop halt?

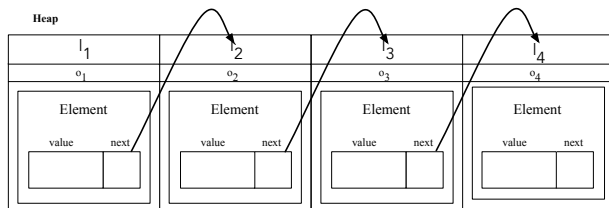
Scenario

Given the following Java instructions,

```
while (x != null)
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Does the loop halt?

- Assuming $\rho(x) = l_1$ before starting the loop.



The loop
terminates in 3
iterations!

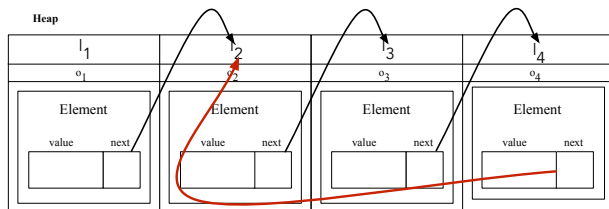
Scenario

Given the following Java instructions,

```
while (x != null)
    x = x.next;
```

Does the loop halt?

- Assuming $\rho(x) = l_1$ before starting the loop.



The loop does not terminate!

It depends on the **cyclicity** of variable x .

Can we refine them?

Yes, by developing a field-sensitive analysis!

```
while (x != null)           x.next = y;  
    x = x.next;
```

Goal

For each program point, maintain a set of **static fields** F such that a program property holds.

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```
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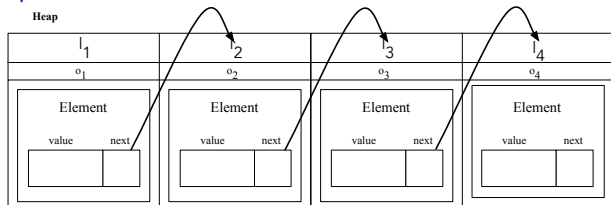
For each program point, maintain a set of **static fields** F such that a program property holds.

We introduce the concept of path \mathcal{P} as a tuple of fields linking two locations inside the heap μ .

e.g., $l_1 \rightsquigarrow_{\mu}^{\mathcal{P}} l_4$

with $\mathcal{P} =$

$\langle El.next, El.next, El.next \rangle$



Field-sensitive properties

Let

- \mathcal{F} : set of all fields;
- $L_\sigma(x)$: set of all locations reachable from x .

Unreachability for each path from x to y in state σ , the fields in F are not part of that path.

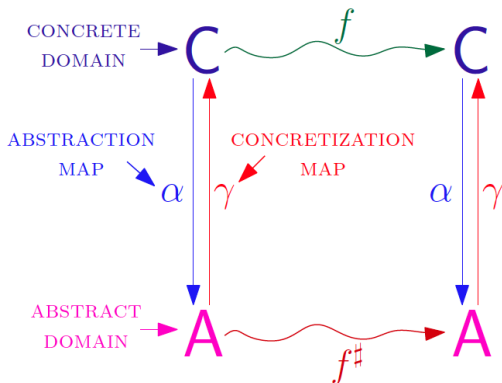
$$\forall \mathcal{P} \subseteq \mathcal{F} \ (x \rightsquigarrow_\sigma^{\mathcal{P}} y \implies \mathcal{P} \cap F = \emptyset) \equiv x \not\rightsquigarrow_\sigma^F y$$

Non-cyclicity for each cycle reachable from x in state σ , the fields in F are not part of the cycle.

$$\forall \ell \in L_\sigma(x), \forall \mathcal{P} \subseteq \mathcal{F} \ (\ell \rightsquigarrow_\mu^{\mathcal{P}} \ell \implies \mathcal{P} \cap F = \emptyset) \equiv x \rightsquigarrow_\sigma^{\emptyset F}$$

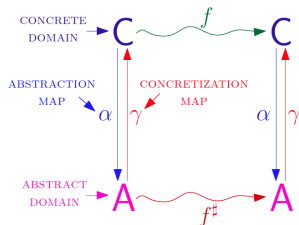
Abstract Interpretation

In order to make our analysis computable, we use the general framework of **Abstract Interpretation**.



Concrete and Abstract Domains

- Σ - set of all states
- V - set of all variables
- \mathcal{F} - set of all program fields



- Concrete domain: $C = \wp(\Sigma)$
- Abstract domain: $A = \wp(V \times V \times \wp(\mathcal{F})) \cup \wp(V \times \wp(\mathcal{F}))$
- Concretization map $\gamma: A \rightarrow C$

$$\gamma(I \in A) = \left\{ \sigma \in \Sigma \mid \left(\forall a \not\rightarrow^F b \in I, \exists F' \subseteq \mathcal{F}. a \not\rightarrow_{\sigma}^{F'} b \wedge F \subseteq F' \right) \wedge \left(\forall c \rightsquigarrow^{\emptyset F} \in I, \exists F' \subseteq \mathcal{F}. c \rightsquigarrow_{\sigma}^{\emptyset F'} \wedge F \subseteq F' \right) \right\}$$

Our properties are **under-approximated** by the information in I .

Methodology

1 Program Under Analysis

```
class Element{
    private Object value;
    private Element prec, next;

    public Element(Object value){
        this.value=value;
    }
    public Element(Object value, Element prec){
        this.value=value;
        this.prec=prec;
        prec.next=this;
    }
}

public class MWexample{
    public static void main(String[] args){
        Element top = new Element(new Integer(0));
        for(int i=1;i<=3;i++)
            top = new Element(new Integer(i),top);
    }
}
```

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```

2 Java Bytecode

```
invokespecial #1 <Object/<init>()V>
aload_0
aload_1
putfield #2 Element.value: Object
aload_0
aload_2
putfield #3 Element.prec: Element
aload_2
aload_0
putfield #4 Element.next: Element
return
```

Methodology

1 Program Under Analysis

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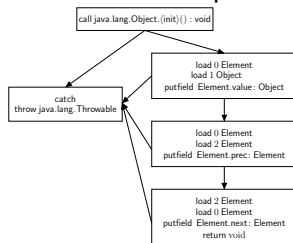
    public Element(Object value){
        this.value=value;
    }
    public Element(Object value, Element prec){
        this.value=value;
        this.prec=prec;
        prec.next=this;
    }
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public class MExample{
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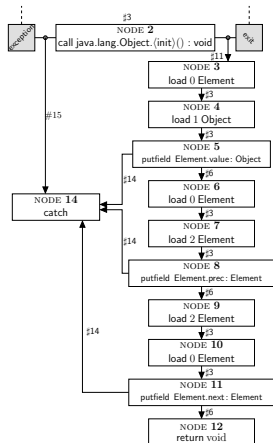
3 Control Flow Graph



Constraint Based Static Analysis

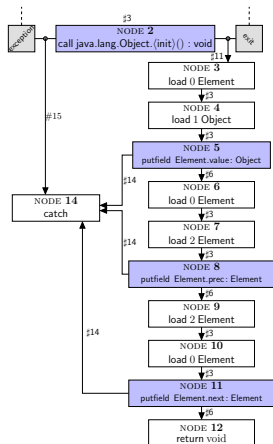
From the Control Flow Graph we build the **Abstract Constraint Graph**

- **Nodes** represent bytecode instructions.
- **Arcs** represent the **abstract semantics**.
- Each node is decorated with an abstract set I .
- Each arc is decorated with a propagation rule.
- **Propagation Rules $\#i$**
 - defined for each type of arc, depending on its sources;
 - state how the information in each node is propagated.



Propagation Rules

- Their definitions can become complex whenever they exploit other static analyses.
- The unreachability and non-cyclicity information is propagated along the arcs of the ACG until reaching a **fix-point**.
- It exists since they are all **monotonic** functions.
- The fix-point is the **maximal** solution of the ACG with respect to the partial order \supseteq .



Example: putfield $\kappa.f:t$ ins: $\Sigma \rightarrow \Sigma'$

$$\begin{array}{c}
 \text{local vars} \quad \text{stack vars} \\
 \lambda \langle \langle l, s_{j-1} :: s_{j-2} :: s \rangle, \mu \rangle . \langle \langle l, s \rangle, \mu [(\mu(s_{j-2}).\phi)(f) \mapsto s_{j-1}] \rangle \\
 \underbrace{\hspace{10em}}_{\rho}
 \end{array}$$

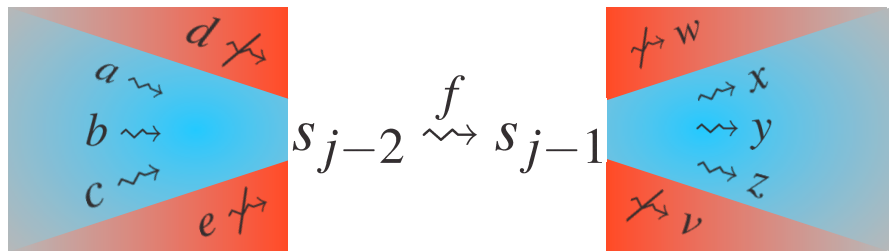
$$s_{j-2} \xrightarrow{f} s_{j-1}$$

It changes the paths between locations!

How to correctly propagate the information w.r.t this instruction?

KEY IDEA: exploit the result of the *possible* reachability analysis.

$$\langle x, y \rangle \notin MR_{\tau} \implies x \not\rightsquigarrow y$$

Example: putfield $\kappa.f:t$ (cont.)

e.g., field-sensitive unreachability

- for each $d \not\rightarrow^F w$ such that $d \not\rightarrow s_{j-2} \vee s_{j-1} \not\rightarrow w$, F does not change after the putfield node.
- for each $a \not\rightarrow^F x$ such that $\langle a, s_{j-2} \rangle, \langle s_{j-1}, x \rangle \in \mathcal{MR}_\tau$, F probably changes:
for sure, after the putfield, F does not contain the field f !

Conclusions

- 1 Build an **under-approximated** analysis to state two **field-sensitive** properties.

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 let $\Rightarrow^* \langle \boxed{\text{ins}} \parallel \sigma \rangle$ be an execution and l_{ins} the approx information,
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Future works: implementing this analysis in **Julia Tool** to improve the precision of its **termination checker**.

Thank You

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